

7. The Stability Theorem

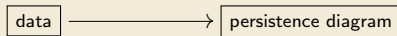
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CBMS Lecture Series, Macalester College, June 2017

The Persistence Stability Theorem

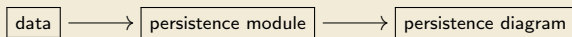
Stability Theorem (Cohen-Steiner, Edelsbrunner, Harer 2007)

The following transformation is Lipschitz:

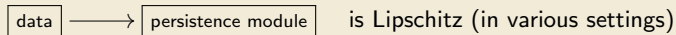


Small changes in the data lead to small changes in the diagram.

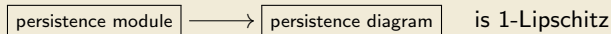
Factorization



Geometric Stability



Algebraic Stability (Chazal, Cohen-Steiner, Glisse, Guibas, Oudot 2009)



Simplex stream

Let S be a finite simplicial complex.

Let $f : S \rightarrow \mathbb{R}$ be a function with the property that

$$f^{-1}(-\infty, t]$$

is a subcomplex of S for every $t \in \mathbb{R}$.

Processing

Run the persistence algorithm on the sequence of simplices ordered by f -value.

Metric

Two such functions $f, g : S \rightarrow \mathbb{R}$ are compared by the supremum norm:

$$\|f - g\|_{\infty} = \max_{\sigma \in S} |f(\sigma) - g(\sigma)|$$

Sublevelset filtration

Let M be a compact smooth manifold.

Let $f : M \rightarrow \mathbb{R}$ be a Morse function (critical points nondegenerate)

Processing

Compute the persistence diagram of

$$H_*(f^{-1}(-\infty, a_0]) \longrightarrow \dots \longrightarrow H_*(f^{-1}(-\infty, a_n])$$

where $a_0 < \dots < a_n$ are the critical values.

Metric

Two such functions $f, g : M \rightarrow \mathbb{R}$ are compared by the supremum norm:

$$\|f - g\|_\infty = \max_{x \in M} |f(x) - g(x)|$$

Sublevelset filtration

Let P be a compact polyhedron (\Leftrightarrow realization of a simplicial complex).

Let $f : P \rightarrow \mathbb{R}$ be a piecewise-linear map.

Processing

Compute the persistence diagram of

$$H_*(f^{-1}(-\infty, a_0]) \longrightarrow \dots \longrightarrow H_*(f^{-1}(-\infty, a_n])$$

where $a_0 < \dots < a_n$ are the critical values.

Metric

Two such functions $f, g : P \rightarrow \mathbb{R}$ are compared by the supremum norm:

$$\|f - g\|_\infty = \max_{x \in P} |f(x) - g(x)|$$

Metric data (fixed set)

Let X be a finite set.

Let $d : X \times X \rightarrow \mathbb{R}$ be a metric.

Processing

Compute the persistence diagram of

$$H_*(\text{VR}((X, d), r_0)) \longrightarrow \dots \longrightarrow H_*(\text{VR}((X, d), r_n))$$

where $r_0 < \dots < r_n$ are the values taken by the metric.

Metric

Two such metrics $d, e : X \times X \rightarrow \mathbb{R}$ are compared by the supremum norm:

$$\|d - e\|_\infty = \max_{x, y \in P} |d(x, y) - e(x, y)|$$

Metric data (subsets of a fixed space)

Let (Z, d) be a metric space.

Let $X \subseteq Z$ be a finite subset.

Processing

Compute the persistence diagram of

$$H_* \left(\text{VR}((X, d), r_0) \right) \longrightarrow \dots \longrightarrow H_* \left(\text{VR}((X, d), r_n) \right)$$

where $r_0 < \dots < r_n$ are the values taken by the metric restricted to X .

Metric

Two such subsets $X, Y \subseteq Z$ are compared by the **Hausdorff distance**:

$$d_H(X, Y) = \max \left[\left(\max_{x \in X} d(x, Y) \right), \left(\max_{y \in Y} d(y, X) \right) \right]$$

Metric data (general)

Let (X, d) be a finite metric space.

Processing

Compute the persistence diagram of

$$H_*(\text{VR}((X, d), r_0)) \longrightarrow \dots \longrightarrow H_*(\text{VR}((X, d), r_n))$$

where $r_0 < \dots < r_n$ are the values taken by the metric.

Metric

Two metric spaces (X, d) , (Y, e) are compared using the **Gromov–Hausdorff** distance:

$$d_{\text{GH}}((X, d), (Y, e)) = \inf_{Z, f, g} [d_{\text{H}}(f(X), g(Y))]$$

The min is taken over all metric spaces Z and isometric embeddings $f : X \rightarrow Z$, $g : Y \rightarrow Z$.

Persistence modules indexed by \mathbb{R} (Chazal et al. 2009)

For the stability theorem, we need to work with real index values.

A **persistence module indexed by \mathbb{R}** is specified by the following data:

- A vector space V_t for every $t \in \mathbb{R}$.
- A linear map $v_t^s : V_s \rightarrow V_t$ whenever $s \leq t$.

We require $v_t^t = 1_{V_t}$ for all t , and $v_u^t v_t^s = v_u^s$ whenever $s \leq t \leq u$.

Henceforth, all persistence modules will be indexed by \mathbb{R} unless stated otherwise.

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Tameness

A persistence module is of **finite type** if there is a finite set of critical values

$$a_0 < a_1 < \cdots < a_n$$

such that

- $V_t = 0$ for all $t < a_0$; and
- V_t is constant, and finite dimensional, over each interval $[a_k, a_{k+1})$.

(Here we take $a_{n+1} = +\infty$.)

Persistence modules indexed by \mathbb{R} (Chazal et al. 2009)

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Tameness

A persistence module is **q-tame** if v_t^s has finite rank whenever $s < t$.

Fact

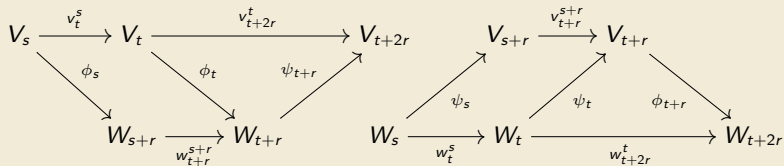
q-tame persistence modules have well-behaved persistence diagrams.

The interleaving distance (Chazal et al. 2009)

An r -**interleaving** between persistence modules V, W is a collection of maps

$$\phi_t : V_t \rightarrow W_{t+r}, \quad \psi_t : W_t \rightarrow V_{t+r}$$

such that the diagrams



commute for all $s < t$.

A 0-interleaving is an isomorphism of persistence modules.

The **interleaving distance** between V, W is

$$d_I(V, W) = \inf_{r \geq 0} \{r \mid \text{there exists an } r\text{-interleaving between } V, W\}$$

Simplex streams

Let S be a simplicial complex and let $f, g : S \rightarrow \mathbb{R}$ define simplex streams.

Suppose $\|f - g\|_\infty \leq r$. Writing

$$[f]^t = f^{-1}(-\infty, t], \quad [g]^t = g^{-1}(-\infty, t],$$

we have inclusions

$$[f]^t \subseteq [g]^{t+r}, \quad [g]^t \subseteq [f]^{t+r}.$$

More generally, we have diagrams

$$\begin{array}{ccccc}
 [f]^s & \longrightarrow & [f]^t & \longrightarrow & [f]^{t+2r} & & [f]^{s+r} & \longrightarrow & [f]^{t+r} \\
 & \searrow & & \searrow & \nearrow & & & \nearrow & & \searrow \\
 & & [g]^{s+r} & \longrightarrow & [g]^{t+r} & & [g]^s & \longrightarrow & [g]^t & \longrightarrow & [g]^{t+2r}
 \end{array}$$

which automatically commute, since all arrows are inclusion maps.

Applying homology H_* , we obtain the maps ϕ_t, ψ_t and required relations for an r -interleaving between the persistence modules for the two simplex streams.

Sublevelset filtrations

Let M be a compact smooth manifold with Morse functions $f, g : M \rightarrow \mathbb{R}$.

Suppose $\|f - g\|_\infty \leq r$. Writing

$$[f]^t = f^{-1}(-\infty, t], \quad [g]^t = g^{-1}(-\infty, t],$$

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 \end{array}$$

which automatically commute, since all arrows are inclusion maps.

Applying homology H_* , we obtain the maps ϕ_t, ψ_t and required relations for an r -interleaving between the persistence modules for the two sublevelset filtrations.

Sublevelset filtrations

Let P be a compact polyhedron with piecewise linear maps $f, g : P \rightarrow \mathbb{R}$.

Suppose $\|f - g\|_\infty \leq r$. Writing

$$[f]^t = f^{-1}(-\infty, t], \quad [g]^t = g^{-1}(-\infty, t],$$

we have inclusions

$$[f]^t \subseteq [g]^{t+r}, \quad [g]^t \subseteq [f]^{t+r}.$$

More generally, we have diagrams

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 \end{array}$$

which automatically commute, since all arrows are inclusion maps.

Applying homology H_* , we obtain the maps ϕ_t, ψ_t and required relations for an r -interleaving between the persistence modules for the two sublevelset filtrations.

Metric data (fixed set)

Let X be a finite set and let $d, e : X \times X \rightarrow \mathbb{R}$ be metrics.

Suppose $\|d - e\|_\infty \leq r$. Writing

$$[d]^t = \text{VR}((X, d), t) \quad [e]^t = \text{VR}((X, e), t)$$

we have inclusions

$$[d]^t \subseteq [e]^{t+r}, \quad [e]^t \subseteq [d]^{t+r}.$$

More generally, we have diagrams

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 & & & \nearrow & \\
 & & & & [d]^{s+r} \longrightarrow [d]^{t+r} \\
 & & & & \nearrow & \searrow \\
 & & & & [e]^s & \longrightarrow & [e]^t & \longrightarrow & [e]^{t+2r}
 \end{array}$$

which automatically commute, since all arrows are inclusion maps.

Applying homology H_* , we obtain the maps ϕ_t, ψ_t and required relations for an r -interleaving between the two Vietoris–Rips homology persistence modules.

More subtle

The other two examples are slightly more subtle:

Metric data (subsets of a fixed space)

Let $X, Y \subseteq Z$ be finite subsets of a fixed metric space (Z, d) .

Metric data (general)

Let $(X, d), (Y, e)$ be finite metric spaces.

Multivalued maps

Let X, Y be sets. A **multivalued map** $F : X \rightrightarrows Y$ is a function

$$F : X \rightarrow \mathcal{P}(Y)$$

that carries each $x \in X$ to a nonempty subset of Y .

Selections

A **selection** from F is a function $f : X \rightarrow Y$ such that $f(x) \in F(x)$ for all x .

Subordinate maps

Let $F, G : X \rightrightarrows Y$. We say that G is **subordinate** to F , and write $G \subseteq F$, if

$$G(x) \subseteq F(x)$$

for all x . Equivalently, every selection from G is a selection from F .

Multivalued simplicial maps

Let S, T be simplicial complexes with vertex sets X, Y .

A **multivalued simplicial map** $F : S \rightrightarrows T$ is a multivalued map $F : X \rightrightarrows Y$, such that the image of every simplex $\sigma \in S$

$$F\sigma = \bigcup_{x \in \sigma} F(x)$$

(has the property that every finite subset) is a simplex of T .

Induced homology map

Let $F : S \rightrightarrows T$ be a multivalued simplicial map. Then the maps

$$f_* : H_*(S) \rightarrow H_*(T)$$

induced by selections f are all equal to each other. Call this map F_* .

Proof

Indeed, any two selections are contiguous.

Remark

It is immediate that $G \subseteq F$ implies $G_* = F_*$.

Metric data (subsets of a fixed space)

Let $X, Y \subseteq Z$ be finite subsets of a fixed metric space (Z, d) .

Suppose $d_H(X, Y) \leq r/2$. Then we can define multivalued maps:

$$F : X \rightrightarrows Y; \quad F(x) = \{y \in Y \mid d(x, y) \leq r/2\}.$$

$$G : Y \rightrightarrows X; \quad G(y) = \{x \in X \mid d(y, x) \leq r/2\}.$$

Using the triangle inequality, these define multivalued simplicial maps

$$F : \text{VR}(X, t) \rightrightarrows \text{VR}(Y, t + r),$$

$$G : \text{VR}(Y, t) \rightrightarrows \text{VR}(X, t + r).$$

Applying homology, we get maps

$$\phi_t = F_* : H_*(\text{VR}(X, t)) \rightrightarrows H_*(\text{VR}(Y, t + r))$$

$$\psi_t = G_* : H_*(\text{VR}(Y, t)) \rightrightarrows H_*(\text{VR}(X, t + r))$$

It remains to verify the required relations for an r -interleaving.

Metric data (subsets of a fixed space)

Let $X, Y \subseteq Z$ be finite subsets of a fixed metric space (Z, d) .

Write $[X]^t = \text{VR}(X, t)$ and $[Y]^t = \text{VR}(Y, t)$. Then we have:

$$\begin{array}{ccccccc}
 [X]^s & \longrightarrow & [X]^t & \longrightarrow & [X]^{t+2r} & & [X]^{s+r} \longrightarrow [X]^{t+r} \\
 \searrow & & \searrow & & \nearrow & & \nearrow \\
 & & [Y]^{s+r} & \longrightarrow & [Y]^{t+r} & & \\
 & & \nearrow & & \nearrow & & \nearrow \\
 & & [Y]^s & \longrightarrow & [Y]^t & \longrightarrow & [Y]^{t+2r}
 \end{array}$$

The two parallelograms commute.

The triangles don't commute. However, the horizontal map in each triangle is subordinate to the composite of the two diagonal maps.

Applying homology, the resulting diagrams do commute.

Thus the maps ϕ_t, ψ_t define an r -interleaving.

Conclusion

subset of a metric space \longrightarrow VR persistent homology is 2 -Lipschitz.

Diagrams

A **diagram in \mathcal{H}** is a multiset of points in the region of the extended plane

$$\mathcal{H} = \{(p, q) \mid -\infty < p < q \leq +\infty\}$$

Point metric

We use the ℓ^∞ metric for points in this region:

$$d^\infty((p_1, q_1), (p_2, q_2)) = \begin{cases} \max(|p_1 - p_2|, |q_1 - q_2|) & \text{if } q_1, q_2 \text{ are finite} \\ |p_1 - p_2| & \text{if } q_1 = q_2 = +\infty \\ \infty & \text{otherwise} \end{cases}$$

We also note the distance from the diagonal:

$$d^\infty((p, q), \Delta) = \frac{1}{2}(q - p)$$

The bottleneck distance

Let A, B be diagrams in \mathcal{H} .

An r -**matching** is a partial bijection between the multisets A, B such that:

- If $a \in A$ and $b \in B$ are matched, then $d^\infty(a, b) \leq r$.
- If $a \in A$ is not matched, then $d^\infty(a, \Delta) \leq r$.
- If $b \in B$ is not matched, then $d^\infty(b, \Delta) \leq r$.

The **bottleneck distance** between A, B is

$$d_B(A, B) = \inf_{r \geq 0} \{r \mid \text{there exists an } r\text{-matching between } A, B\}$$

Algebraic Stability Theorem (Chazal et al. 2009)

If two **q-tame** persistence modules are r -interleaved, then their persistence diagrams are r -matched.

persistence module \longrightarrow persistence diagram is 1-Lipschitz

Ingredients

- Box Lemma.
- Glisse Interpolation Lemma.

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Ingredients

- **Box Lemma.**
- Glisse Interpolation Lemma.

Box Lemma

Let V, W be r -interleaved persistence modules with persistence diagrams A, B .

Then the number of points of A inside any rectangle R is no greater than the number of points of B inside the rectangle R^r obtained by thickening R on both sides by r (provided that R^r does not meet the diagonal).

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persistence module \longrightarrow persistence diagram is 1-Lipschitz

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Glisse Interpolation Lemma

Let V, W be r -interleaved persistence modules.

Then there is a 1-parameter family of persistence modules

$$(V_t \mid t \in [0, r])$$

such that $V_0 = V$ and $V_r = W$, with the additional property that V_s, V_t are $|s - t|$ -interleaved for all s, t .

Box Lemma

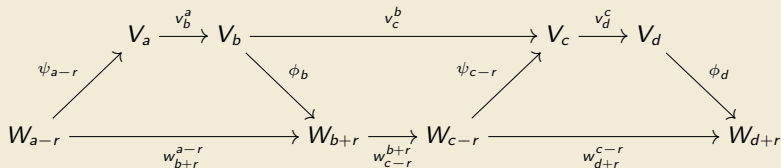
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Outline Proof

Let $R = [a, b] \times [c, d]$ so that $R^r = [a - r, b + r] \times [c - r, d + r]$.

Consider the diagram:



Box Lemma

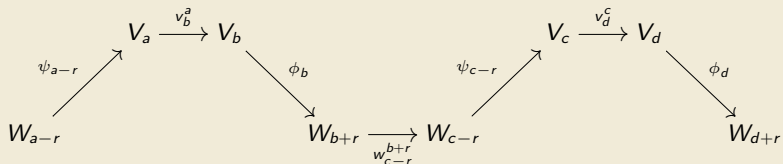
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Outline Proof

Let $R = [a, b] \times [c, d]$ so that $R^r = [a - r, b + r] \times [c - r, d + r]$.

$$W_{a-r} \rightarrow V_a \rightarrow V_b \rightarrow W_{b+r} \rightarrow W_{c-r} \rightarrow V_c \rightarrow V_d \rightarrow W_{d+r}$$

Rectangle point counts are obtained by counting interval summands:

$\#[B \cap R^r] :$			
$\#[A \cap R] :$			

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Remarks

- The lemma can be proved by direct algebraic construction; or by applying the Kan Extension Theorem from category theory.
- The lemma can be **circumvented** if the initial data can be interpolated.

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Set $f_t = (1 - t)f + tg$.

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Sublevelset filtrations

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Metric data (fixed set)

Let X be a finite set and let $d, e : X \times X \rightarrow \mathbb{R}$ be metrics.

Set $d_t = (1 - t)d + te$.

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Metric data (subsets of a fixed space)

Let $X, Y \subseteq Z$ be finite subsets of a fixed metric space (Z, d) .

Set

$$X_t = \{(1 - t)x + ty \mid x \in X, y \in Y, d(x, y) \leq d_H(X, Y)\}.$$

Outline proof of Algebraic Stability Theorem

- The Box Lemma can be used to show that



is locally 1-Lipschitz (near persistence modules with a finite diagram).

- Local 1-Lipschitz implies global 1-Lipschitz, by applying a Heine–Borel argument along a path provided by the Glisse Interpolation Lemma.