

## 3. Persistence

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# The homology of a planar region

## Chain complex

We have constructed a diagram of vector spaces and linear maps

$$0 \longleftarrow \xrightarrow{\partial_{-1}} C_0(U) \longleftarrow \xrightarrow{\partial_0} C_1(U) \longleftarrow \xrightarrow{\partial_1} C_2(U)$$

for any plane region  $U \subseteq \mathbb{R}^2$ .

From this we define

$$Z_k(U) = \ker(\partial_{k-1}) \quad \text{the space of } k\text{-cycles}$$

$$B_k(U) = \text{im}(\partial_k) \quad \text{the space of } k\text{-boundaries}$$

Since  $\partial_{k-1}\partial_k = 0$ , we have  $B_k \leq Z_k$ . Since  $\partial_{-1} = 0$  we have  $Z_0 = C_0$ .

## Homology = Cycles/Boundaries

$$H_0(U) = \frac{\ker(\partial_{-1})}{\text{im}(\partial_0)} = \frac{Z_0(U)}{B_0(U)} = \frac{C_0(U)}{B_0(U)}$$

$$H_1(U) = \frac{\ker(\partial_0)}{\text{im}(\partial_1)} = \frac{Z_1(U)}{B_1(U)}$$

Homology = Cycles/Boundaries

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The **Betti numbers** of  $U$  are defined as follows:

$$b_0(U) = \dim(H_0(U))$$

$$b_1(U) = \dim(H_1(U))$$

## Theorem

Let  $U \subseteq \mathbb{R}^2$  be open. Then  $b_0(U) = \#$  connected components of  $U$ .

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## Proof

For simplicity assume finitely many components  $U_1, \dots, U_k$ .  
Select points  $p_i \in U_i$ . Then  $[p_i] \in C_0(U)$ .

- $[p_1], \dots, [p_k]$  span  $C_0(U)$  modulo  $B_0(U)$ .
- $[p_1], \dots, [p_k]$  are linearly independent modulo  $B_0(U)$ .

We must show that every 0-chain can be written in the form

$$\alpha = \lambda_1[p_1] + \dots + \lambda_k[p_k] + \partial\gamma.$$

Indeed, every generator can be written in this form. Specifically,

$$[a] = [p_i] + \partial\gamma$$

where

$$\gamma = [p_i, a_1] + [a_1, a_2] + \dots + [a_n, a]$$

for some polygonal path  $P(p_i, a_1, a_2, \dots, a_n, a)$  in  $U$ .

# The homology of a planar region

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- $[p_1], \dots, [p_k]$  are linearly independent modulo  $B_0(U)$ .

Suppose

$$\lambda_1[p_1] + \dots + \lambda_k[p_k] + \partial\gamma = 0$$

Consider the linear maps  $\mu_i : C_0(U) \rightarrow \mathbb{F}$  defined on generators by:

$$\mu_i([a]) = \begin{cases} 1 & \text{if } a \in U_i \\ 0 & \text{if } a \notin U_i \end{cases}$$

Then  $\mu_i \partial = 0$  since the endpoints of each edge must lie in the same component.  
Applying  $\mu_i$  to the equation yields  $\lambda_i = 0$ .

## Theorem

Let  $U = \mathbb{R}^2 - \{a_1, a_2, \dots, a_\ell\}$  where the  $a_i$  are distinct. Then  $b_1(U) = \ell$ .

# The homology of a planar region

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## Proof

Let  $\gamma_i \in Z_1(U)$  denote a small counterclockwise square around  $a_i$ .

- $\gamma_1, \dots, \gamma_\ell$  span  $Z_1(U)$  modulo  $B_1(U)$ .
- $\gamma_1, \dots, \gamma_\ell$  are linearly independent modulo  $B_1(U)$ .

Suppose

$$\lambda_1 \gamma_1 + \dots + \lambda_\ell \gamma_\ell + \partial\sigma = 0$$

Consider the linear maps  $w_i : Z_1(U) \rightarrow \mathbb{F}$  defined by:

$$w_i(\zeta) = w(\zeta, a_i).$$

We have seen that  $w_i \partial = 0$  in  $\mathbb{R}^2 - \{a_1, \dots, a_\ell\}$ .

Applying  $w_i$  to the equation yields  $\lambda_i = 0$ .



# The homology of a planar region

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- $\gamma_1, \dots, \gamma_\ell$  span  $Z_1(U)$  modulo  $B_1(U)$ .
- $\gamma_1, \dots, \gamma_\ell$  are linearly independent modulo  $B_1(U)$ .

We must show that every 1-cycle can be written in the form

$$\zeta = \lambda_1 \gamma_1 + \dots + \lambda_\ell \gamma_\ell + \partial\sigma.$$

Write  $\lambda_i = w(\zeta, a_i)$  and replace  $\zeta$  by  $\zeta - (\lambda_1 \gamma_1 + \dots + \lambda_\ell \gamma_\ell)$ . This has winding number zero about every  $a_i$ .

Partition the plane into a fine rectangular grid. By subtracting boundaries, we can reduce  $\zeta$  to a cycle of grid edges. By subtracting boundaries of grid rectangles, we can reduce to the case that  $w(\zeta, a) = 0$  for every non-grid point  $a$ . By considering rays, it follows that we are reduced to the case  $\zeta = 0$ .

# The homology of a planar region

## Dual bases

We have dual bases in the two proofs.

We have

$$[p_1], [p_2], \dots, [p_k] \quad \text{and} \quad \mu_1, \mu_2, \dots, \mu_k$$

such that

$$\mu_i \partial = 0 \quad \text{and} \quad \mu_i [p_j] = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

which guarantees that  $b_0 \geq k$ .

We have

$$\gamma_1, \gamma_2, \dots, \gamma_\ell \quad \text{and} \quad w_1, w_2, \dots, w_\ell$$

such that

$$w_i \partial = 0 \quad \text{and} \quad w_i \gamma_j = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

which guarantees that  $b_1 \geq \ell$ .

For the upper bounds, we used ad hoc geometric constructions.

## Cochains

A  **$k$ -cochain** is a linear map  $T : C_k \rightarrow \mathbb{F}$ . The collection of all  $k$ -cochains is denoted by the symbol  $C^k$ :

$$C^k(U; \mathbb{F}) = \text{Hom}(C_k(U; \mathbb{F}), \mathbb{F})$$

## Cocycles

A  $k$ -cochain  $T$  is a  **$k$ -cocycle** if  $T\partial = 0$ . A  $k$ -cocycle can be thought of as a linear map

$$T : (C_k/B_k) \rightarrow \mathbb{F}.$$

This restricts to a linear map

$$T : (Z_k/B_k) \rightarrow \mathbb{F}.$$

The collection of  $k$ -cocycles is denoted  $Z^k$ .

## Coboundaries

A  $k$ -cochain of the form  $T = S\partial$  is called a  **$k$ -coboundary**. Such a cochain restricts to the zero map on  $Z_k$  and hence on  $H_k = Z_k/B_k$ .

The collection of  $k$ -coboundaries is denoted  $B^k$ . We have  $B^k \subseteq Z^k \subseteq C^k$ .

## Cohomology

We define the  $k$ -cohomology to be  $H^k = Z^k/B^k$ .

## Duality Theorem

The vector space  $H^k$  is the dual of  $H_k$ :

$$H^k \cong \text{Hom}(H_k, \mathbb{F})$$

## Construction of the isomorphism

We have seen that a cocycle defines a map on homology. We get a linear map

$$Z^k \rightarrow \text{Hom}(Z_k/B_k, \mathbb{F}).$$

Since coboundaries define the zero map, we get

$$(Z^k/B^k) \rightarrow \text{Hom}(Z_k/B_k, \mathbb{F}).$$

It is not difficult to show that the map is surjective and injective.

**Main Lemma:** A linear map defined on a subspace can be extended to the whole vector space. (Fails for modules over a commutative ring.)

# The cohomology of a planar region

Example: winding number cocycles

Define cochains  $W, X_\phi : C_1(\mathbb{R}^2 - \{0\}) \rightarrow \mathbb{R}$  by

$$W[a, b] = \frac{1}{2\pi} \Lambda([a, b], 0)$$
$$X_\phi[a, b] = \begin{cases} +1 & \text{if } [a, b] \text{ crosses } R_\phi \text{ counterclockwise} \\ -1 & \text{if } [a, b] \text{ crosses } R_\phi \text{ clockwise} \\ 0 & \text{if } [a, b] \text{ doesn't meet } R_\phi \end{cases}$$

They are cocycles, so they define maps  $H_1 \rightarrow \mathbb{R}$ .

They differ by a coboundary

$$W = \left(\frac{1}{2\pi} \overline{\arg}_\phi\right) \partial + X_\phi$$

thanks to the formula

$$\Lambda([a, b], 0) = \overline{\arg}_\phi(b) - \overline{\arg}_\phi(a) + 2\pi\xi_j$$

so they define the same map on  $H_1$ .

## Dual complexes

We have defined a homology chain complex

$$0 \longleftarrow C_0(U) \xleftarrow{\partial_0} C_1(U) \xleftarrow{\partial_1} C_2(U)$$

and its dual, a cohomology cochain complex

$$0 \longrightarrow C^0(U) \xrightarrow{\delta^0} C^1(U) \xrightarrow{\delta^1} C^2(U)$$

using algebraic versions of points, edges, and triangles.

(Here  $\delta^k$  is the operation 'pre-compose with  $\partial_k$ '.)

Our homology theory is the homology of 'linear singular simplices'.



## Abstract simplicial complexes

A simplicial complex is a set  $S$  of nonempty finite sets which is closed under taking subsets:

$$\sigma \in S \text{ and } \emptyset \neq \tau \subseteq \sigma \text{ implies } \tau \in S$$

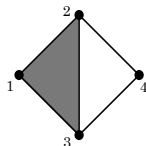
## Example

The set

$$M = \{\{2, 4\}, \{3, 4\}, \{1, 2, 3\}\}$$

is not a simplicial complex, but its closure under taking subsets is:

$$S = \{\{1\}, \{2\}, \{3\}, \{4\}, \{1, 2\}, \{1, 3\}, \{2, 3\}, \{2, 4\}, \{3, 4\}, \{1, 2, 3\}\}$$



We write  $S = \langle 1, 2, 3, 4, 12, 13, 24, 34, 123 \rangle = \langle 24, 34, 123 \rangle$ .



## Vertices

The **vertex set** of a simplicial complex  $S$  is

$$V = V(S) = \bigcup S$$

In the example above,  $V = \{1, 2, 3, 4\}$ .

## Simplices

An element of  $S$  is called a **simplex** (plural **simplices**).

If  $\sigma \in S$  has  $k + 1$  elements, we call it a  $k$ -simplex, and write  $\dim \sigma = k$ .

## Subcomplexes

A **subcomplex** is a subset of a simplicial complex that is a simplicial complex. The  **$k$ -skeleton** of  $S$  is the subcomplex of simplices of dimension at most  $k$ .

## Geometric realisation

Let  $S$  be a simplicial complex with vertex set  $V$ . Its **geometric realization** is the subspace of  $\mathbb{R}^V$  defined as follows:

$$|S| = \left\{ f : V \rightarrow \mathbb{R} \mid f \geq 0, f^{-1}(\mathbb{R} - \{0\}) \in S, \sum_{v \in V} f(v) = 1 \right\}$$

Each vertex  $w$  corresponds to a delta function:  $\delta_w(v) = \begin{cases} 1 & \text{if } v = w \\ 0 & \text{if } v \neq w \end{cases}$

(Caution: If  $V$  is infinite, there are two reasonable topologies on  $|S|$ : the product topology and the Whitehead topology. They agree when  $S$  is locally finite.)

## Shadow map

Any function  $\phi : V \rightarrow \mathbb{R}^n$  gives rise to a map  $\Phi : |S| \rightarrow \mathbb{R}^n$ , defined by the formula

$$\Phi(f) = \sum_{v \in V} f(v)\phi(v).$$

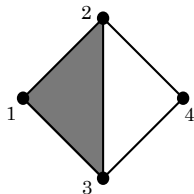
It is a continuous map (with respect to the Whitehead topology).

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It is a continuous map (with respect to the Whitehead topology).



## Philosophy

In topological data analysis, we work with abstract simplicial complexes. If the vertices are taken from data points in  $\mathbb{R}^n$ , then we may also consider the shadow map. This is rarely injective.

## Vietoris–Rips complex

Let  $X$  be a metric space, and let  $R \geq 0$ . The **Vietoris–Rips complex** with diameter  $R$  is the simplicial complex with vertex set  $X$  defined by the condition:

$$\sigma = \{x_0, x_1, \dots, x_n\} \in \text{VR}(X, R) \Leftrightarrow d(x_i, x_j) \leq R \text{ for all } 0 \leq i, j \leq n$$

It is the **clique complex** for the neighbourhood graph of diameter  $R$ .

## Example

Let  $X$  be a finite collection of robotic sensors located in the plane. The Coverage Theorem uses the 2-skeleton:

$$\text{VR}(X, R)^{(2)} \subseteq \text{VR}(X, R)$$

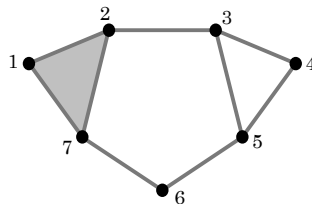
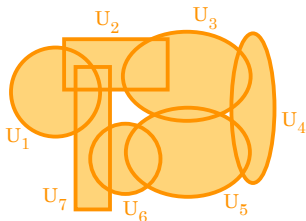
The fence cycle  $\gamma$  is built from 1-simplices.

Coverage is determined in terms of (the shadows of) the 2-simplices.

## The nerve of a set system

Let  $U_1, \dots, U_n$  be sets, and write  $\mathcal{U} = (U_1, \dots, U_n)$ . The **nerve** of  $\mathcal{U}$  is a simplicial complex on the vertex set  $\{1, 2, \dots, n\}$  defined by the following condition:

$$\sigma \in \text{Nerve}(\mathcal{U}) \Leftrightarrow \bigcap_{k \in \sigma} U_k \neq \emptyset$$



## The Nerve Theorem (Leray, Borsuk, etc)

For a family of convex subsets of a vector space, the nerve is a good model for the union of the family.

## Čech complex

Let  $X \subset \mathbb{R}^N$ , and let  $r \geq 0$ . The **Čech complex** with radius  $r$  is the simplicial complex with vertex set  $X$  defined by the condition:

$$\sigma = \{x_0, x_1, \dots, x_n\} \in \check{\text{Cech}}(X, r) \\ \Leftrightarrow \text{there exists } p \in \mathbb{R}^N \text{ with } |p - x_i| \leq r \text{ for all } i$$

It is the nerve of the set of closed disks with centers  $x_i$  and radius  $r$ .  
By the Nerve theorem, it is a good model for the union of those disks.

## Dowker complex

Let  $X, Y$  be sets, let  $\phi : X \times Y \rightarrow \mathbb{R}$ , and let  $t \in \mathbb{R}$ . The **Dowker complex** with parameter  $t$  is the simplicial complex with vertex set  $X$  defined by the condition:

$$\sigma = \{x_0, x_1, \dots, x_n\} \in \text{Dowker}(\phi, t) \\ \Leftrightarrow \text{there exists } y \in Y \text{ with } \phi(x_i, y) \leq t \text{ for all } i$$

## Dowker duality

$\text{Dowker}(\phi, t)$  and  $\text{Dowker}(\phi^T, t)$  are good models for each other.

## Comparing the Vietoris–Rips and Čech complexes

Let  $X \subset \mathbb{R}^N$ . Then

$$\check{\text{Cech}}(X, r) \subseteq \text{VR}(X, 2r)$$

and

$$\text{VR}(X, R) \subseteq \check{\text{Cech}}(X, R\sqrt{N/(2N+2)})$$

The second inclusion is Jung's Theorem.

## Philosophy

In this way the two methods of simplicial approximation are **interleaved**.

In Euclidean space of any dimension, we deduce

$$\text{VR}(X, R) \subseteq \check{\text{Cech}}(X, R/\sqrt{2}).$$

In dimension 2, we get the  $\sqrt{3}$ -Lemma

$$\text{VR}(X, R) \subseteq \check{\text{Cech}}(X, R/\sqrt{3})$$

which relates the two forms of sensor network coverage discussed earlier.





## Goal

From a simplicial complex  $S$ , we wish to define a diagram of vector spaces and linear maps

$$0 \longleftarrow C_0(S) \xleftarrow{\partial_0} C_1(S) \xleftarrow{\partial_1} C_2(S) \xleftarrow{\partial_2} C_3(S) \xleftarrow{\partial_3} \dots$$

satisfying  $\partial^2 = 0$ . This is the **simplicial chain complex** of  $S$ .

We also have the dual diagram

$$0 \longrightarrow C^0(S) \xrightarrow{\delta^0} C^1(S) \xrightarrow{\delta^1} C^2(S) \xrightarrow{\delta^2} C^3(S) \xrightarrow{\delta^3} \dots$$

satisfying  $\delta^2 = 0$ . This is the **simplicial cochain complex** of  $S$ .

## Homology

$$Z_k = \ker \partial_{k-1}, \quad B_k = \text{im } \partial_k, \quad H_k = Z_k/B_k.$$

## Cohomology

$$Z^k = \ker \delta^k, \quad B^k = \text{im } \delta^{k-1}, \quad H^k = Z^k/B^k.$$

## Simplicial $k$ -chains

We define  $C_k(S; \mathbb{F})$  in terms of generators and relations:

- a generator  $[a_0, a_1, \dots, a_k]$  whenever  $\{a_0, a_1, \dots, a_k\} \in S$ ,
- the relation  $[a_0, a_1, \dots, a_k] = 0$  if the  $a_i$  are not distinct;
- the relation

$$[a_0, a_1, \dots, a_k] = (-1)^\sigma [a_{\sigma(0)}, a_{\sigma(1)}, \dots, a_{\sigma(k)}]$$

for any permutation  $\sigma$ .

## Alphabetical convention

Given a total ordering of the vertices of  $S$ , the elements

$[a_0, a_1, \dots, a_k]$  such that  $a_0 < a_1 < \dots < a_k$  and  $\{a_0, a_1, \dots, a_k\} \in S$

constitute a basis for  $C_k$ . Thus  $\dim C_k$  is equal to the number of  $k$ -simplices.

## Simplicial $k$ -chains

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- the relation

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for any permutation  $\sigma$ .

## Boundary map

The boundary map  $\partial_k : C_{k+1} \rightarrow C_k$  is defined on generators by

$$\partial_k [a_0, \dots, a_{k+1}] = \sum_{i=0}^{k+1} (-1)^i [\dots, \hat{a}_i, \dots]$$

where  $[\dots, \hat{a}_i, \dots]$  denotes the result of deleting  $a_i$  from  $[a_0, \dots, a_{k+1}]$ .

The boundary maps are well-defined, and  $\partial^2 = 0$ .

## Simplicial $k$ -cochains

We define  $C^k(S; \mathbb{F})$  to be the space of  $\mathbb{F}$ -valued functions

$$F(a_0, a_1, \dots, a_k)$$

defined for  $(a_0, a_1, \dots, a_k)$  such that  $\{a_0, a_1, \dots, a_k\} \in S$ , and satisfying

- $F(a_0, a_1, \dots, a_k) = 0$  if the  $a_i$  are not distinct, and
- $F(a_0, a_1, \dots, a_k) = (-1)^\sigma F(a_{\sigma(0)}, a_{\sigma(1)}, \dots, a_{\sigma(k)})$  for any permutation  $\sigma$ .

## Coboundary map

The coboundary map  $\delta^k : C^k \rightarrow C^{k+1}$  is defined by the formula

$$[\delta^k F](a_0, \dots, a_{k+1}) = \sum_{i=0}^{k+1} (-1)^i F(\dots, \hat{a}_i, \dots)$$

where  $(\dots, \hat{a}_i, \dots)$  denotes the result of deleting  $a_i$  from  $(a_0, \dots, a_{k+1})$ .

The coboundary maps are well-defined, and  $\delta^2 = 0$ .



## Simplicial maps

Let  $S, T$  be simplicial complexes with respective vertex sets  $V, W$ .  
A **simplicial map**  $f : S \rightarrow T$  is a function

$$f : V \rightarrow W$$

such that  $f\{a_0, a_1, \dots, a_k\} \in T$  whenever  $\{a_0, a_1, \dots, a_k\} \in S$ .

Write ' $f\sigma \in T$  whenever  $\sigma \in S$ ' for conciseness.

## Induced chain map

A simplicial map  $f : S \rightarrow T$  induces a family of maps

$$f_* : C_k(S) \rightarrow C_k(T)$$

by the formula  $f_*[a_0, a_1, \dots, a_k] = [f(a_0), f(a_1), \dots, f(a_k)]$ .

## Induced homology map

Since  $\partial f_* = f_* \partial$ , this induces maps on homology

$$f_* : H_k(S) \rightarrow H_k(T).$$

## Simplicial maps

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Write ' $f\sigma \in T$  whenever  $\sigma \in S$ ' for conciseness.

## Induced cochain map

A simplicial map  $f : S \rightarrow T$  induces a family of maps

$$f^* : C^k(T) \rightarrow C^k(S)$$

by the formula  $[f_*F](a_0, a_1, \dots, a_k) = F(f(a_0), f(a_1), \dots, f(a_k))$ .

## Induced cohomology map

Since  $f^*\delta = \delta f^*$ , this induces maps on cohomology

$$f_* : H^k(T) \rightarrow H^k(S).$$

## Contiguous maps

Two simplicial maps  $f, g : S \rightarrow T$  are **contiguous** if

$$f\sigma \cup g\sigma \in T$$

whenever  $\sigma \in S$ .

## Theorem

Contiguous simplicial maps  $f, g : S \rightarrow T$  give rise to equal maps in homology

$$f_* = g_* : H_k(S) \rightarrow H_k(T)$$

and cohomology

$$f^* = g^* : H^k(T) \rightarrow H^k(S).$$





## Philosophy of Topological Data Analysis

A finite data set  $X$  is given:

- metric space or similarity space; or
- subset of  $\mathbb{R}^N$ .

Construct a 1-parameter family of simplicial complexes  $S(r)$  that 'approximate'  $X$  at different scales:

$$S(r_0) \xrightarrow{\subseteq} S(r_1) \xrightarrow{\subseteq} \cdots \xrightarrow{\subseteq} S(r_n)$$

Compute their homology

$$H_k(S(r_0)) \longrightarrow H_k(S(r_1)) \longrightarrow \cdots \longrightarrow H_k(S(r_n))$$

or cohomology

$$H^k(S(r_0)) \longleftarrow H^k(S(r_1)) \longleftarrow \cdots \longleftarrow H^k(S(r_n))$$

Invariants of the resulting diagrams are multiscale descriptors of the data.