Definition. A symmetry of a square is a motion that, when applied to the square, places the square in the same space that it originally occupied.

Demonstration:

Note:
$$r_{90} = r_{450} = r_{810} = \cdots$$

Notation: r_{90} is a counterclockwise rotation of the square (about its center) by 90°.

$$r_{90} \begin{pmatrix} \boxed{1} & 2 \\ 4 & 3 \end{pmatrix} = \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix}$$

Key: Think of r_{90} as a function whose input/output is a square.

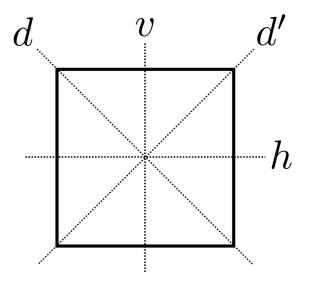
Discuss in your group: Describe all symmetries of a square.

The symmetries of a square are:

• 4 rotations: r_0 , r_{90} , r_{180} , r_{270}

Note: r_0 is often denoted ε and is called the identity.

• 4 reflections: h, v, d, d'. (These are the axis of reflection.)



Let D_4 be the set of symmetries of a square, i.e.,

$$D_4 = \{\varepsilon, r_{90}, r_{180}, r_{270}, h, v, d, d'\}.$$

- We can compose symmetries to obtain other symmetries.
- Analogy: We can add integers to obtain other integers.

"Composed with" **Example:** $d \circ r_{90} = v$, because...

Remark: This is just like $(f \circ g)(x) = f(g(x))$.

In today's Class Work, you'll complete a composition table for D_4 :

		Inside function					190 0 d = ?			
	0	arepsilon	red	r_{180}	r_{270}	h	v		$\int d'$	
Function	ε									
	r_{90}			r_{270}		d'	d	h	v	
	r_{180}					v		d'	d	
	r_{270}					d	d'	v	h	
کی ا	h		d	v	d'		r_{180}	r_{90}	r_{270}	
Jutside	v		d'		d	r_{180}		r_{270}	r_{90}	
			γV	d'	h	r_{270}	r_{90}		r_{180}	
	d'		h	d	v		r_{270}	r_{180}		
			do 10	no = V						

0	ε	r_{90}	r_{180}	r_{270}	h	ig v	d	d'
ε	ε	r_{90}	r_{180}	r_{270}	h	v	d	d'
r_{90}	r_{90}	r_{180}	r_{270}	ε	d'	d	h	v
r_{180}	r_{180}	r_{270}	arepsilon	r_{90}	v	h	d'	d
r_{270}	r_{270}	ε	r_{90}	r_{180}	d	d'	v	h
(h)	h	d	v	d'	ε	r_{180}	r_{90}	r_{270}
v	v	d'	h	d	r_{180}	arepsilon	r_{270}	r_{90}
d	d	v	d'	h	r_{270}	r_{90}	ε	r_{180}
d'	d'	h	d	$oxed{v}$	r_{90}	r_{270}	r_{180}	arepsilon

Inverse examples:

- \bullet h is a self-inverse
- $r_{90} \circ r_{270} = \varepsilon$

inverse pair

Group properties:

- \checkmark 1. D_4 is closed.
- \checkmark 2. Associative law, i.e., $(\sigma \circ \tau) \circ \mu = \sigma \circ (\tau \circ \mu)$. (Yes. We'll see why soon.)
- ✓ 3. The *identity* element ε is in D_4 . $\xi \circ \mathcal{G} = \mathcal{G}$, $\mathcal{G} \circ \xi = \mathcal{G}$.
- \checkmark 4. Every element in D_4 has an *inverse*.

Take $h \in D_4$, i.e., the horizontal reflection. Then...

$$C(h) = \{ \sigma \in D_4 \mid \sigma \circ h = h \circ \sigma \}$$
 (i.e., elements that commute with h .)

is called the *centralizer* of h in D_4 .

Elements:

- $\varepsilon \in C(h)$, because $\varepsilon \circ h = h \circ \varepsilon$.
- $r_{180} \in C(h)$, because $r_{180} \circ h = h \circ r_{180}$.
- $h \in C(h)$, because $h \circ h = h \circ h$.
- $v \in C(h)$, because $v \circ h = h \circ v$.

Conclusion:

 $C(h) = \{\varepsilon, \ r_{180}, \ h, \ v\}$ (It's a subset of D_4 .)

• Also, $r_{90} \notin C(h)$, since $r_{90} \circ h \neq h \circ r_{90}$. (Likewise for all other elements of D_4 .)

Table for $C(h) = \{ \varepsilon, r_{180}, h, v \}$:

0	arepsilon	r_{180}	h	$oxed{v}$
arepsilon	ε	r_{180}	h	v
r_{180}	r_{180}	ε	v	h
h	h	v	ε	r_{180}
v	$\mid v \mid$	h	r_{180}	ε

Conclusion: C(h) is a subgroup of D_4 .

Group properties:

- 1. C(h) is closed.
- 2. Associative law, i.e., $(\sigma \circ \tau) \circ \mu = \sigma \circ (\tau \circ \mu)$. (Yes. We'll see why soon.)
- 3. C(h) contains the identity ε .
- 4. Elements in C(h) have inverses.